# **Distributed Laplacian Solving with Applications**

Sebastian Forster, né Krinninger

University of Salzburg

SIROCCO 2022

Joint work with Gramoz Goranci, Yang P. Liu, Richard Peng, Xiaorui Sun, Tijn de Vos, and Mingquan Ye







#### Der Wissenschaftsfonds.

This project has received funding from the European Research Council (ERC) under the European Union's Horizon 2020 research and innovation programme (grant agreement No 947702). Supported by the Austrian Science Fund (FWF): P 32863-N



# Laplacian Paradigm

- Laplacian systems
- Spectral sparsifiers
- Electrical flow
- Effective resistance
- Expander decompositions
- Continuous optimization
- Interior-point methods
- Gradient descent
- Preconditioning



• ...

# Laplacian Paradigm and Distributed Computing

## Observation

Laplacian paradigm often yields inherently parallelizable algorithms

# Laplacian Paradigm and Distributed Computing

## Observation

Laplacian paradigm often yields inherently parallelizable algorithms

## **Basic operation:**

- Vector **x**: each node represents a coordinate
- Matrix A: each edge represents a non-zero entry
- Matrix-vector multiplication Ax: one round

# Laplacian Paradigm and Distributed Computing

#### Observation

Laplacian paradigm often yields inherently parallelizable algorithms

## **Basic operation:**

- Vector **x**: each node represents a coordinate
- Matrix A: each edge represents a non-zero entry
- Matrix-vector multiplication Ax: one round

State of the art for (approximate) single-source shortest path, maximum flow, minimum-cost flow:

[Ghaffari, Karrenbauer, Kuhn, Lenzen, Patt-Shamir '15] [Becker, F, Karrenbauer, Lenzen '17] [Zuzic '21] [Anagnostides, Themis Gouleakis, Christoph Lenzen '21] [Zuzic, Goranci, Ye, Haeupler, Sun '22] [Rozhon, Grunau, Haeupler, Zuzic, Li '22]

## Goal

Solve linear system Lx = b such that L is a Laplacian matrix.

#### Goal

Solve linear system Lx = b such that L is a Laplacian matrix.

## Definition

The **Laplacian matrix** L(G) of graph G = (V, E, w) is defined by

$$\mathbf{L}(G)_{u,v} = \begin{cases} \sum_{(u,v')\in E} w_{u,v'} & \text{if } u = v, \\ -w_{u,v} & \text{otherwise.} \end{cases}$$

#### Goal

Solve linear system Lx = b such that L is a Laplacian matrix.

#### Definition

The **Laplacian matrix** L(G) of graph G = (V, E, w) is defined by

$$\mathbf{L}(G)_{u,v} = \begin{cases} \sum_{(u,v')\in E} w_{u,v'} & \text{if } u = v, \\ -w_{u,v} & \text{otherwise.} \end{cases}$$

High-precision solver: Approximation of solution  $\mathbf{x}^*$  with  $\mathbf{x}$  s.t.

$$\|\mathbf{x} - \mathbf{x}^*\|_{\mathbf{L}(G)} \le \epsilon \|\mathbf{b}\|_{\mathbf{L}(G)}.$$

#### Goal

Solve linear system Lx = b such that L is a Laplacian matrix.

#### Definition

The **Laplacian matrix** L(G) of graph G = (V, E, w) is defined by

$$\mathbf{L}(G)_{u,v} = \begin{cases} \sum_{(u,v')\in E} w_{u,v'} & \text{if } u = v, \\ -w_{u,v} & \text{otherwise.} \end{cases}$$

High-precision solver: Approximation of solution  $\mathbf{x}^*$  with  $\mathbf{x}$  s.t.

$$\|\mathbf{x} - \mathbf{x}^*\|_{\mathbf{L}(G)} \le \epsilon \|\mathbf{b}\|_{\mathbf{L}(G)}.$$

## Prior work:

- $\tilde{O}(m)$  sequential running time [Spielman, Teng '04]
- $\tilde{O}(m)$  work, polylogarithmic depth [Peng, Spielman '14]

## **CONGEST** Model



- · Edges correspond to non-zero entries of matrix
- · Each node holds one row/column of matrix
- · Communication over edges in synchronous rounds
- Bandwidth  $O(\log n)$  per edge

# **Our Results for the CONGEST Model**

Theorem ([F, Goranci, Liu, Peng, Sun, Ye])

In the CONGEST model, given a weighted and undirected graph *G* and a vector **b** on *n* vertices, we can in  $O(n^{o(1)}(\sqrt{n} + D))$  rounds return a vector **x** such that  $||\mathbf{x} - \mathbf{x}^*||_{\mathbf{L}(G)} \le \epsilon ||\mathbf{b}||_{\mathbf{L}(G)}$ .

Almost matches a  $\tilde{\Omega}(\sqrt{n} + D)$  lower bound

# Our Results for the CONGEST Model

Theorem ([F, Goranci, Liu, Peng, Sun, Ye])

In the CONGEST model, given a weighted and undirected graph G and a vector **b** on n vertices, we can in  $O(n^{o(1)}(\sqrt{n} + D))$  rounds return a vector **x** such that  $||\mathbf{x} - \mathbf{x}^*||_{\mathbf{L}(G)} \le \epsilon ||\mathbf{b}||_{\mathbf{L}(G)}$ .

Almost matches a  $\tilde{\Omega}(\sqrt{n} + D)$  lower bound

## Implications

 $\tilde{O}\left(m^{3/7+o(1)}(n^{1/2}D^{1/4}+D)\right)$ -round algorithms in CONGEST model for the following problems:

- Maximum flow [Mądry '16]
- Unit capacity minimum cost flow [Cohen et al. '17]
- Negative weight shortest path [Cohen et al. '17]

First o(n)-round algorithms for sparse, low-diameter graphs

# **Approximate Schur Complement**

## **Definition (Schur complement)**

For an  $n \times n$  symmetric matrix **M** and a subset of *terminals*  $T \subseteq [n]$ , let  $S = [n] \setminus T$ . Permute the rows/columns of **M** to write

$$\mathbf{M} = \begin{bmatrix} \mathbf{M}_{[S,S]} & \mathbf{M}_{[S,T]} \\ \mathbf{M}_{[T,S]} & \mathbf{M}_{[T,T]} \end{bmatrix}$$

Then the *Schur complement* of **M** onto *T* is defined as  $SC(\mathbf{M}, T) := \mathbf{M}_{[T,T]} - \mathbf{M}_{[T,S]}\mathbf{M}_{[S,S]}^{-1}\mathbf{M}_{[S,T]}.$ 

Result of block Gaussian elimination

# **Approximate Schur Complement**

## **Definition (Schur complement)**

For an  $n \times n$  symmetric matrix **M** and a subset of *terminals*  $T \subseteq [n]$ , let  $S = [n] \setminus T$ . Permute the rows/columns of **M** to write

$$\mathbf{M} = \begin{bmatrix} \mathbf{M}_{[S,S]} & \mathbf{M}_{[S,T]} \\ \mathbf{M}_{[T,S]} & \mathbf{M}_{[T,T]} \end{bmatrix}$$

Then the *Schur complement* of **M** onto *T* is defined as  $SC(\mathbf{M}, T) := \mathbf{M}_{[T,T]} - \mathbf{M}_{[T,S]}\mathbf{M}_{[S,T]}^{-1}\mathbf{M}_{[S,T]}.$ 

Result of block Gaussian elimination

Graphical interpretation:



Input graph



Schur complement

# **Approximate Schur Complement**

## **Definition (Schur complement)**

For an  $n \times n$  symmetric matrix **M** and a subset of *terminals*  $T \subseteq [n]$ , let  $S = [n] \setminus T$ . Permute the rows/columns of **M** to write

$$\mathbf{M} = \begin{bmatrix} \mathbf{M}_{[S,S]} & \mathbf{M}_{[S,T]} \\ \mathbf{M}_{[T,S]} & \mathbf{M}_{[T,T]} \end{bmatrix}$$

Then the *Schur complement* of **M** onto *T* is defined as  $SC(\mathbf{M}, T) := \mathbf{M}_{[T,T]} - \mathbf{M}_{[T,S]}\mathbf{M}_{[S,S]}^{-1}\mathbf{M}_{[S,T]}.$ 

Result of block Gaussian elimination

Graphical interpretation:



Input graph



Schur complement





Sparsification

## Problem

Communication of edges "along" sparsifier edges my lead to too much congestion

## Problem

Communication of edges "along" sparsifier edges my lead to too much congestion

Solution

Vertex sparsifiers as minors of the communication graph





## Problem

Communication of edges "along" sparsifier edges my lead to too much congestion

Solution

Vertex sparsifiers as **minors** of the communication graph



#### Lemma

*Matrix-vector multiplication involving minor sparsifier takes*  $\tilde{O}(\sqrt{n} + D)$  *rounds.* 

## Problem

Communication of edges "along" sparsifier edges my lead to too much congestion

Solution

Vertex sparsifiers as minors of the communication graph



#### Lemma

Matrix-vector multiplication involving minor sparsifier takes  $\tilde{O}(\sqrt{n} + D)$  rounds.

Key contribution: Parallel variant of [Li Schild '18]

• From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - Obtain Schur complement from sampling random walks

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - · Obtain Schur complement from sampling random walks
  - Algorithmically: estimate of *congestion* in random walks

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - · Obtain Schur complement from sampling random walks
  - Algorithmically: estimate of congestion in random walks
  - Computation introduces round-overhead of (log<sup>c</sup> n)<sup>d</sup>; can only work with d = O(log log n) → sophisticated recursion

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - · Obtain Schur complement from sampling random walks
  - Algorithmically: estimate of congestion in random walks
  - Computation introduces round-overhead of (log<sup>c</sup> n)<sup>d</sup>; can only work with d = O(log log n) → sophisticated recursion
- Minor sparsifiers: avoid sequential sampling of [Li Schild '18]

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - · Obtain Schur complement from sampling random walks
  - Algorithmically: estimate of congestion in random walks
  - Computation introduces round-overhead of (log<sup>c</sup> n)<sup>d</sup>; can only work with d = O(log log n) → sophisticated recursion
- Minor sparsifiers: avoid sequential sampling of [Li Schild '18]
  - Identify "steady" edges that can be sampled independently
  - Requires recursive solution of linear system: edge reduction via ultra-sparsifiers

- From [Kyng, Lee, Peng, Sachdeva, Spielman '16]: Repeated elimination of **almost independent sets** yields vertex sparsifier "chain" with recursion depth *d* = *O*(log *n*)
  - Fast computation of inverse of submatrix of eliminated nodes using iterative method
- In addition to Schur complement itself, we need to compute further information (linear operators)
  - · Obtain Schur complement from sampling random walks
  - Algorithmically: estimate of congestion in random walks
  - Computation introduces round-overhead of (log<sup>c</sup> n)<sup>d</sup>; can only work with d = O(log log n) → sophisticated recursion
- Minor sparsifiers: avoid sequential sampling of [Li Schild '18]
  - Identify "steady" edges that can be sampled independently
  - Requires recursive solution of linear system: edge reduction via ultra-sparsifiers
  - Distortion of minor property in recursive calls

## What Next?

## Implications

 $\tilde{O}\left(m^{3/7+o(1)}(n^{1/2}D^{1/4}+D)\right)$ -round algorithms in CONGEST model for the following problems:

- Maximum flow [Mądry '16]
- Unit capacity minimum cost flow [Cohen et al. '17]
- Negative weight shortest path: [Cohen et al. '17]

## What Next?

## Implications

 $\tilde{O}\left(m^{3/7+o(1)}(n^{1/2}D^{1/4}+D)\right)$ -round algorithms in CONGEST model for the following problems:

- Maximum flow [Mądry '16]
- Unit capacity minimum cost flow [Cohen et al. '17]
- Negative weight shortest path: [Cohen et al. '17]

## Question

Sublinear #rounds in dense graphs?

## Implications

 $\tilde{O}\left(m^{3/7+o(1)}(n^{1/2}D^{1/4}+D)\right)$ -round algorithms in CONGEST model for the following problems:

- Maximum flow [Mądry '16]
- Unit capacity minimum cost flow [Cohen et al. '17]
- Negative weight shortest path: [Cohen et al. '17]

## Question

Sublinear #rounds in dense graphs?

## **Easier Question**

Sublinear #rounds on the Broadcast Congested Clique?

## **Broadcast Congested Clique**



- Nodes can communicate with all other nodes [Lotker et al. '05]
- Broadcast *the same* message to all nodes [Drucker, Kuhn, Oshman '12]

## **Broadcast Congested Clique**



- Nodes can communicate with all other nodes [Lotker et al. '05]
- Broadcast *the same* message to all nodes [Drucker, Kuhn, Oshman '12]
- For many problems: only "trivialization" of CONGEST model upper bounds with *D* = 1 is known

Theorem ([F, de Vos '22])

On the Broadcast Congested Clique, the minimum cost flow problem can be solved in  $\tilde{O}(\sqrt{n})$  rounds.

**Theorem (**[F, de Vos '22])

On the Broadcast Congested Clique, the minimum cost flow problem can be solved in  $\tilde{O}(\sqrt{n})$  rounds.

## **Other Results:**

- On the Broadcast Congested Clique, a spectral sparsifier of quality  $1 \pm \epsilon$  and size  $\tilde{O}(n/\epsilon^2)$  can be computed in  $\tilde{O}(1/\epsilon^2)$  rounds
- On the Broadcast Congested Clique, a Laplacian system can be solved up to high accuracy in  $\tilde{O}(\log^2(1/\epsilon))$  rounds
- On the Broadcast Congested Clique, certain Linear Programs can be solved in  $\tilde{O}(\sqrt{n})$  rounds.

## **Linear Programming**

Minimize  $\mathbf{c}^{\mathsf{T}}\mathbf{x}$  subject to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ 

**Linear Programming** Minimize  $\mathbf{c}^{\mathsf{T}}\mathbf{x}$  subject to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ 

Implementation of [Lee, Sidford '14]:

- Interior point method with  $\tilde{O}(\sqrt{\text{rank}})$  iterations
- · One linear system solve per iteration

**Linear Programming** Minimize  $\mathbf{c}^{\mathsf{T}}\mathbf{x}$  subject to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ 

Implementation of [Lee, Sidford '14]:

- Interior point method with  $\tilde{O}(\sqrt{\text{rank}})$  iterations
- · One linear system solve per iteration

Minimum cost flow:

- Rank = #nodes
- · Linear system has Laplacian matrix

# **Key Contribution**

Iterative computation of spectral sparsifier [Koutis, Xu '16]:

- · Compute a spanner
- · Sample non-spanner edges with constant probability

# **Key Contribution**

Iterative computation of spectral sparsifier [Koutis, Xu '16]:

- · Compute a spanner
- Sample non-spanner edges with constant probability

#### Problem

On Broadcast Congested Clique, nodes cannot easily coordinate with neighbors on sampling incident edges

# **Key Contribution**

Iterative computation of spectral sparsifier [Koutis, Xu '16]:

- · Compute a spanner
- Sample non-spanner edges with constant probability

#### Problem

On Broadcast Congested Clique, nodes cannot easily coordinate with neighbors on sampling incident edges

## Solution:

- Compute spanner on "probabilistic" graph
- Sample individual edges ad-hoc when needed
- Modification of spanner algorithm of [Baswana, Sen '07]

[Lee, Sidford '14]: #iterations:  $\tilde{O}(\sqrt{n})$ Time per iteration:  $\tilde{O}(m)$  [Chen et al. '22]: #iterations:  $m^{1+o(1)}$ Time per iteration:  $m^{o(1)}$  [Lee, Sidford '14]: #iterations:  $\tilde{O}(\sqrt{n})$ Time per iteration:  $\tilde{O}(m)$ 

Iteration count carries over to round complexity

[Chen et al. '22]: #iterations:  $m^{1+o(1)}$ Time per iteration:  $m^{o(1)}$ 

Running time improvement does not improve round complexity [Lee, Sidford '14]: #iterations:  $\tilde{O}(\sqrt{n})$ Time per iteration:  $\tilde{O}(m)$ 

Iteration count carries over to round complexity

[Chen et al. '22]: #iterations:  $m^{1+o(1)}$ Time per iteration:  $m^{o(1)}$ 

Running time improvement does not improve round complexity

#### Question

Is  $\tilde{\Theta}(\sqrt{n})$  the right iteration count for min-cost flow LP?

## Question

Is  $\tilde{\Theta}(\sqrt{n})$  the right round complexity for min-cost flow in the BCC?

## Question

Is  $\tilde{\Theta}(\sqrt{n})$  the right round complexity for min-cost flow in the BCC?

Lower bounds in BCC at least not hopeless
 [Frischknecht, Holzer, Wattenhofer '12] [Drucker, Kuhn,
 Oshman '14] [Censor-Hillel, Kaski, Korhonen, Lenzen, Paz,
 Suomela] [Holzer, Pinsker '15] [Becker, Montealegre, Rapaport,
 Todinca '18]

## Question

Is  $\tilde{\Theta}(\sqrt{n})$  the right round complexity for min-cost flow in the BCC?

- Lower bounds in BCC at least not hopeless
   [Frischknecht, Holzer, Wattenhofer '12] [Drucker, Kuhn,
   Oshman '14] [Censor-Hillel, Kaski, Korhonen, Lenzen, Paz,
   Suomela] [Holzer, Pinsker '15] [Becker, Montealegre, Rapaport,
   Todinca '18]
- Better upper bound already interesting for single-source reachability

# Conclusion



# Almost optimal Laplacian solvers

## Conclusion





# Almost optimal Laplacian solvers

Broadcast Congested Clique is an interesting "burning glass"