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Evolving Topologies of Artificial Neural Networks Adapted to Image Processing Tasks

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Abstract - **Artificial Neural Networks (ANN) have gained increasing popularity as an alternative to statistical methods for classification of Remote Sensing Data. Their superiority to some of the classical statistical methods has been shown in the literature. Therefore, ANNs are commonly used for segmentation and classification purposes. We address the problem of generating an appropriate network topology, the right number of training epochs and preprocessing the training data set for multi-layer feed-forward ANNs. A method based on Genetic Algorithms (GA) for the automatic generation of problem–adapted topologies is employed with the parallel netGEN system which has been designed by the authors. A land cover classification problem using multi–spectral Landsat Thematic Mapper (TM) data is presented so as to demonstrate the capabilities of netGEN.**

I. INTRODUCTION

Results on the successful application of ANNs in the field of Remote Sensing Data Analysis have been reported, e.g. Bischof *et al.* [1] and Civco [2] on Landsat TM images, Wu *et al.* [3] on SPOT images and Wilkinson *et al.* [4] on a combination of ERS-1 SAR and Landsat TM images. ANNs assume no distributional form for the class densities which is an advantage over statistical classifiers and has also been studied in recent years [5].

A problem which has not been investigated in detail in recent papers, although, it was mentioned in [1] and [2], is the problem of finding the appropriate topology (structure), e.g. the number of nodes, layers, connections, the connectivity, of the ANN. Commonly, a satisfying ANN topology is found by experiments or by applying rules–of–thumb.

We use a GA to adapt the ANN topology to our specific image processing task. Each individual of a generation, a neural network in a population of ANNs, is trained and tested so as to evaluate ANN performance and to assign a fitness to the individual. After a selection process the individuals with the highest fitness are used to form the next generation.

netGEN has been implemented as a parallel system where the learning of the ANNs is distributed among several workstations. The learning of the individual ANN is performed by an ANN simulator, namely, the *SNNS* (Stuttgart Neural Network Simulator) [6]. For the message passing between the individual modules we employed the *PVM* (Parallel Virtual Machine) library [7].

As an example for the performance of ANNs created by netGEN, we address a land cover classification of a part of the Austrian National Park "Hohe Tauern", an alpine region with elevations ranging from about 1000 meters up to 2500 meters. The data set consists of the 6 non-thermal Landsat TM bands and a *DEM* (Digital Elevation Model) which has also been used for prior geo–coding. A ground–truth map containing 35 land cover classes as the result of a ground data collection campaign is available.

II. EVOLUTION OF ARTIFICIAL NEURAL NETWORKS

Various methods have been suggested for the automatic construction of ANN topologies. Among these are *Network Growing* (OBS [8], OBD [9], etc.), *Network Pruning* (Cascade Correlation [10], etc.), and *Evolutionary Design* of networks. In the netGEN system we chose the latter approach by employing Genetic Algorithms. We restricted the genetic search to Feed–Forward Networks which are trained by standard Error–Back–Propagation with a fixed *learn rate* and no *momentum term*.

Out of numerous existing genotype representations of an ANN [11], we adopted a *direct encoding* method introduced by *Miller & Todd* [12]. Their original encoding - in the following called *Miller–Matrix* (MM) - uses an adjacency matrix to represent the topology of an ANN. Each entry $w_{ij} \in \{0(\text{no connection}), L(\text{learnable connection})\}$ in the matrix at position (i, j) indicates the absence or presence of a directed connection between unit j and unit

i. Further, they added a column for the biases of the units.

In our *Modified–Miller–Matrix* MMM encoding scheme [13] we dropped the bias column and added *Neuron Markers* in the main diagonal (i, i) of the MMM, indicating the absence or presence of a particular neuron i. As a consequence, the only topology parameters which have to be set are the number of input and output neurons (depending on the problem) and the maximum number of neurons.

In order to combat overfitting [14], we also encoded the number of training epochs with the additional benefit of another ANN parameter being set automatically.

In addition to our modifications of the MM encoding scheme, the GA does not operate on the matrix representation, but on the concatenation of the rows of the non–zero part of the MMM's lower triangle matrix representing the possible connections. All MMM entries clamped to zero need not be processed by the GA, hence, they are not encoded in the genotype.

The general form of the genotype looks like:

$$e_1 e_2 \dots e_{n_1} m_1 m_2 \dots m_{n_2} x_1 x_2 \dots x_{n_3},$$

where

1. $e_i \in \{0,1\}, i = 1, \dots, n_1$ is the binary representation of the number of epochs,

2. $m_i \in \{0,1\}, i = 1, \dots, n_2$ are the neuron markers, where $m_i = 0$ indicates the absence and $m_i = 1$ indicates the presence of a neuron and

3. $x_i \in \{0,1\}, i = 1, \dots, n_3$ indicate the absence/presence of a connection. The x_i represent possible connections (non–zero entries in the MMM). Reflexive connections, connections within input and output layer, and connections from unit i to unit j with $i < j$, i. e. constant zero entries in the MMM, are not encoded.

This enables the use of the standard genetic operator *2–Point–Crossover* [15] which has a more global effect on the bit string representation (and therefore, the ANN topology) than the MM crossover operator exchanging rows or columns of two individuals. The mutation operator used in netGEN is the standard bit–flip with mutation probability p_m.

For the GA selection phase we chose *Binary Tournament Selection*, for it showed mostly better results than *Proportionate Selection Methods*. First analytical steps, possibly confirming this observation, have been reported recently [16].

Besides a "good" encoding of the problem, the choice of an appropriate fitness function is essential to the GA and its capability of finding (sub)optimal solutions. As for the LULC problem, we experimented with various fitness functions using penalties so as to assess the distance of a misclassification to a correct classification. An ANN whose observed winner neuron in the output layer is close to the wanted winner with one particular test pattern receives a small penalty which increases with distance [17]. However, at the time we arrived at the best solutions with a simple fitness function (the classification accuracy of an individual ANN on the test data set) without penalties.

The following GA and ANN parameters have been used with all the experiments in this paper:
Population Size = 50, Generations = 30, Crossover Probability $p_c = 0.6$, Mutation Probability $p_m = 0.005$, Crossover = 2–Point, Selection Method = Binary Tournament.
Network Topology = Feed–Forward, Transfer Function (all neurons) = Sigmoid, Training = Back–Propagation, Learning Parameter $\eta = 0.2$, No Momentum Term, Number of Epochs = Evolutionary, Training Set Size = 197, Test Set Size = 1000.

III. System Layout and Implementation

The netGEN system [13] has been implemented on a network cluster of SPARC and NeXT workstations in order to parallelize the learning phase of ANNs.

In figure 1 the main components, the Simple Genetic Algorithm (SGA) [18], the Genotype/Phenotype Mapping (GPM), and the Neural Network Manager (NNM), of the netGEN system are shown.

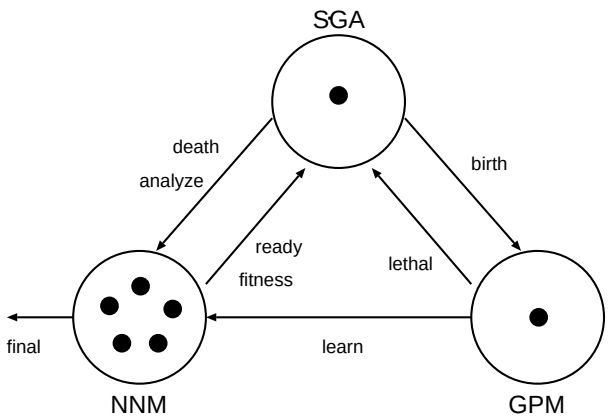

Figure 1: The netGEN system.

SGA generates a blueprint for each ANN, a genotype in GA terminology, which is processed by the GPM module mapping the ANN genotype to a phenotype adapted to the Neural Network Simulator. The mapping module's task is to prepare valid configuration files and to dismiss ANN topologies which cannot be processed by netGEN.

If the topology is valid, a command, e.g. *learn*, is passed to the NNM module. The NNM interfaces to the ANN simulator, evaluates the fitness of each ANN and passes it back to the SGA. With the parallel implementation a set of NNM processes run on different machines and/or different processors.

Furthermore, we like to mention that we achieve *implicit load balancing* which means that more ANNs are passed to the faster machines within the PVM. A simple time–out mechanism prevents the system from deadlock and performance reducing situations when waiting for results from crashed or very slow machines.

IV. DATA PREPROCESSING

The Landsat TM data for the classification test area have been obtained from path 192 for August 7th 1991 at 9:30 am. Landsat TM channel 6, the thermal infrared channel, is not used in the classification data set. The remaining 6 channels have been geo–coded to the grid resolution of 25 meter pixels. The DEM which is available at a resolution of 50 meters has also been oversampled to 25 meter pixel resolution.

Various pixels from the 646 by 661 pixels scene have been selected at random for training and test data sets. The original 35 vegetation classes in the ground–truth (a digital version of the area's vegetation map [19]) have been reduced to 6. This was necessary, because of the similarity of many classes, e.g. 14 types of grassland are distinguished in the map.

The large time lag between the completion of the vegetation map and the Landsat data take results in a degradation of the ground–truth accuracy. Therefore, two filters have been applied in preprocessing, a *k–Nearest Neighbor* (k–NN)–filter in the feature space and another one in the image space.

The use of the k–NN–filter to prevent overfitting has been discussed in [14]. Only training samples with similar spectral signature in terms of the Euklidian distance are retained for a ground–truth class. A training sample is deleted from the pattern set, if the majority of the k neighbors belongs to a different ground–truth class. Thus, spectral coherence is increased for patterns of the same ground–truth class.

The second filter ensures class homogeneity within a $m \times m$ window in the spatial domain, where $k = (m \times m) - 1$, around the pixel in question. A training sample is deleted from the pattern set, if not all pixels in the spatial neighborhood belong to the same ground–truth class. Pixels representing mixed class membership which are found next to class boundaries, eventually, caused by inaccurate ground–truth, are removed by the spatial filter.

V. A LANDSAT TM LAND COVER CLASSIFICATION EXAMPLE

For the given region three classification methods have been applied, a Maximum–Likelihood classification, using the GRASS [20] `i.maxlik` function, an ANN classification using a fully connected ANN with one hidden layer, and an ANN classification using a partially connected topology generated by netGEN (22 Units, 136 Connections, 1430 Epochs). Results are given in table 1 using a confusion table, where the columns are the reference categories, i.e. the ground–truth categories, and the rows are the classification categories. Each entry is given in percent of the number of samples in the considered reference class. Both ANNs were trained using the same training set, the training set for the Maximum–Likelihood classification was obtained using the GRASS function `i.gensig`.

VI. DISCUSSION

As can be seen from table 1, the overall accuracy for the ANN generated by netGEN is 73 percent. Considering the time span of 6 years between vegetation map publication and satellite data take, it is obvious that the 1985 ground–truth is just an approximation to the 1991 land cover. Due to this discrepancy, the relative low accuracy compared to similar work can be explained.

The netGEN ANNs require a surprisingly small training data set (197 samples), although, it has to be mentioned that the performance of a standard topology like the 7–7–6 ANN comes very close to netGEN ANNs by increasing the number of samples in the training data set. We believe that this effect depends mainly on the rather simple fitness function we are currently using, i. e. the netGEN topology could still be improved.

Furthermore, by encoding the number of training epochs in the ANN genotype representation overfitting of netGEN ANNs could not be observed, but this could also be credited to the k–NN filtering or to the specific topology of netGEN ANNs, which will be investigated closely in our future research.

VII. OUTLOOK

We have presented the netGEN system which has been applied to a land cover classification problem and can be used easily for other image processing tasks, e. g. feature extraction, by exchanging training and test data sets and by supplying an appropriate fitness function. Further research interests include an evolutionary approach to the generation of training data sets, evaluation of more complex fitness functions, and experiments with different input representations, e. g. texture, slope.

Table 1: Classification accuracy of different classification methods.

	Maximum–Likelihood						7–7–6 ANN						netGEN ANN					
	1	2	3	4	5	6	1	2	3	4	5	6	1	2	3	4	5	6
1	83.9	43.5	20.1	0.9	0.0	5.7	69.9	22.9	7.9	0.3	0.0	12.3	73.2	26.9	11.0	0.3	0.0	13.6
2	12.3	45.6	19.8	1.5	0.0	0.7	16.4	44.3	13.6	0.6	0.0	1.3	3.0	65.1	2.0	0.1	0.0	2.2
3	2.8	8.5	53.5	38.1	0.8	22.2	13.4	30.6	62.1	14.3	0.0	20.4	21.8	4.4	68.9	14.0	0.0	19.7
4	0.1	0.3	4.4	46.7	19.9	6.1	0.0	1.0	15.0	78.6	28.7	14.2	0.1	0.5	16.1	80.4	34.0	13.1
5	0.0	0.0	0.0	7.4	73.1	4.2	0.0	0.0	0.0	4.8	71.0	3.1	0.0	0.1	0.0	2.8	65.9	2.8
6	0.9	2.1	2.1	5.3	6.1	55.0	0.2	1.2	1.3	1.4	0.2	48.7	1.3	3.0	2.0	2.4	0.1	48.6
	53.6						68.2						73.2					

1...Forest, 2...Shrubs, 3...Grassland, 4...No Vegetation, 5...Glacier, 6...Water

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